

F.A.R.O.

**Single & Dual Antenna GPS-Aided
Inertial Navigation Systems**

INS



ACDU 557

QTYC 17

F.A.R.O.
Via San Marco, 8 - loc. Strassoldo 33052 - Cervignano del Friuli (UD)
Tel: 329 057 8650 Fax: 0434 185 1614 www.faromarine.com

Single and Dual Antenna GPS-Aided INS Specifications

| | Parameter | Units | INS-B (Basic) | INS-P (Professional) | INS-D (Dual Antenna) |
|-----------------------|---|--------------------------|--|--|--|
| | Output signals | | Positions, Heading, GNSS Heading (D model), Pitch & Roll, Heave (D model), Velocity, Accelerations, Angular rates, Barometric data, Pulse Per Second (PPS) | | |
| | Update rate | Hz | 1 ... 200 (user settable) | 1 ... 200 (user settable) | 1 ... 200 (user settable) |
| | Start-up time | sec | <1 | <1 | <1 |
| Navigation | Positions, Velocity and Timestamps | Units | INS-B | INS-P | INS-D |
| | Horizontal position accuracy (GPS L1), RMS | meters | 1.5 | 1.5 | 1.5 |
| | Horizontal position accuracy (GPS L1 & L2), RMS | meters | 1.2 | 1.2 | 1.2 |
| | Horizontal position accuracy (SBAS), RMS ⁽¹⁾ | meters | 0.6 | 0.6 | 0.6 |
| | Horizontal position accuracy (DGPS), RMS | meters | 0.4 | 0.4 | 0.4 |
| | Horizontal position accuracy (post processing) ⁽²⁾ | meters | 0.05 | 0.05 | 0.05 |
| | Horizontal position accuracy (RTK), RMS | meters | 0.01 + 1 ppm | 0.01 + 1 ppm | 0.01 + 1 ppm |
| | Vertical position accuracy, RMS | meters | <1 | <1 | <1 |
| | Velocity accuracy, RMS | meters/sec | 0.03 | 0.03 | 0.03 |
| | PPS timestamps accuracy | milliseconds | <5 | <5 | <5 |
| Orientation | Heading | Units | INS-B | INS-P | INS-D |
| | Range | deg | 0 to 360 | 0 to 360 | 0 to 360 |
| | Static Accuracy ⁽³⁾ | deg | 1 | 0.2 | 0.2 |
| | Dynamic Accuracy ⁽⁶⁾ | deg RMS | 1.5 | 0.4 | 0.4 |
| | Dual antenna GNSS Heading accuracy | deg RMS | - | - | 0.08 (2 meters baseline) |
| Pitch and Roll | Post processing accuracy ⁽¹⁾ | deg RMS | 0.5 | 0.1 | 0.1 |
| | Pitch and Roll | Units | INS-B | INS-P | INS-D |
| | Range: Pitch, Roll | deg | ±90, ±180 | ±90, ±180 | ±90, ±180 |
| | Angular Resolution | deg | 0.01 | 0.01 | 0.01 |
| | Static Accuracy in whole Temperature Range | deg | 0.05 | 0.05 | 0.05 |
| Heave | Dynamic Accuracy ⁽⁶⁾ | deg RMS | 0.1 | 0.1 | 0.1 |
| | Post processing accuracy ⁽¹⁾ | deg RMS | 0.03 | 0.03 | 0.03 |
| | Heave | Units | INS-B | INS-P | INS-D |
| | Measurement range | meters | - | - | ±300 |
| | Resolution | meters | - | - | 0.01 |
| GNSS receiver | Accuracy, RMS | % (meters) | - | - | 5 (0.05) |
| | GNSS receiver | Units | INS-B | INS-P | INS-D |
| GNSS | Number of Antennas | | Single | Single | Dual |
| | Supported navigation signals | | L1 & L2 GPS, GLONASS, GALILEO, BEIDOU, SBAS, DGPS, RTK | | |
| | Channel configuration ⁽⁴⁾ | | 120 Channels | | |
| | GNSS Positions data rate ⁽⁵⁾ | Hz | 20, 50 | | |
| | GNSS Measurements (raw) data rate | Hz | 20 | | |
| | Single antenna Heading accuracy, RMS ⁽⁶⁾ | degree | 0.1 | | |
| | Dual antenna Heading accuracy, RMS | degree | 0.08 (2 meters baseline) | | |
| | Velocity accuracy, RMS | meters/sec | 0.03 | | |
| | Initialization time | Sec | <50 (cold start), <30 (hot start) | | |
| | Time accuracy (clock drift) ⁽⁷⁾ | nano sec | 20 | | |
| Sensors | Gyroscopes | Units | INS-B | INS-P | INS-D |
| | Measurement range | deg/sec | ±450 | ±450 | ±450 |
| | Bias in-run stability (RMS, Allan Variance) | deg/hr | 1 | 1 | 1 |
| | Noise density | deg/sec ² /Hz | 0.004 | 0.004 | 0.004 |
| | Accelerometers | Units | INS-B | INS-P | INS-D |
| | Measurement range | g | ±8 | ±8 | ±8 |
| | Bias in-run stability (RMS, Allan Variance) | mg | 0.005 | 0.005 | 0.005 |
| | Noise density | mg ² /Hz | 0.015 | 0.015 | 0.015 |
| | Magnetometers | Units | INS-B | INS-P | INS-D |
| | Measurement range | Gauss | ±2 | ±1.6 | ±2 |
| Pressure | Bias in-run stability, RMS | nT | 4 | 0.2 | 4 |
| | Noise density, PSD | nT ² /Hz | 10 | 0.3 | 10 |
| | Pressure | Units | INS-B | INS-P | INS-D |
| | Measurement range | hPa | 300 – 1100 | 300 – 1100 | 300 – 1100 |
| | Bias in-run stability (RMS, Allan Variance) | Pa | 2 | 2 | 2 |
| Environment | Noise density | Pa/V/Hz | 0.8 | 0.8 | 0.8 |
| | Environment | Units | INS-B | INS-P | INS-D |
| | Operating temperature | deg C | -40 to +70 | -40 to +70 | -40 to +70 |
| | Storage temperature | deg C | -50 to +85 | -50 to +85 | -50 to +85 |
| | MTBF | hours | 55,500 | 55,500 | 55,500 |
| General | Electrical | Units | INS-B | INS-P | INS-D |
| | Supply voltage | V DC | 9 to 36 | 9 to 36 | 9 to 36 |
| | Power consumption | Watts | 1 | 1.4 | 2.6 |
| | Output Interface | - | RS-232, RS-422, RS-485 | RS-232, RS-422, RS-485 | RS-232, RS-422, RS-485 |
| | Output data format | | Binary, TSS-1, NMEA 0183 ASCII characters | Binary, TSS-1, NMEA 0183 ASCII characters | Binary, TSS-1, NMEA 0183 ASCII characters |
| Physical | Physical | Units | INS-B | INS-P | INS-D |
| | Size | mm | 120 x 50 x 53 | 120 x 50 x 53 | 120 x 50 x 53 |
| | Weight | gram | 220 | 280 | 320 |